L Number	Hits	Search Text	DB	Time stamp
-	273	(901/21).CCLS.	USPAT;	2002/06/18 16:03
			US-PGPUB	
-	82	((901/21).CCLS.) and ratio	USPAT;	2002/06/18 16:08
			US-PGPUB	
-	7	((901/21).CCLS.) and ((tooth or teeth) with ratio)	USPAT;	2002/06/24 14:38
			US-PGPUB	
-	242	(901/40).CCLS.	USPAT;	2002/06/18 16:22
		<u>.</u>	US-PGPUB	
-	255	(414/744.5).CCLS.	USPAT;	2003/10/24 02:17
			US-PGPUB	
-	850	(425/556).CCLS.	USPAT;	2002/06/18 16:41
	_		US-PGPUB	000000000000000000000000000000000000000
-	3	((414/744.5 or 90/40 or 901/21).CCLS.) and ((tooth or teeth)	USPAT;	2002/06/24 14:41
	_	with ratio with pulley)	US-PGPUB	0000/40/04 00 05
-	0	((414/744.5 or 90/40 or 901/21).CCLS.) and (((tooth or teeth)	USPAT;	2003/10/24 02:05
	_	adj3 ratio) with pulley)	US-PGPUB	00000000000000
-	0	((414/\$ or 901/\$).CCLS.) and (((tooth or teeth) adj3 ratio) with	USPAT;	2002/06/24 14:44
	_	pulley)	US-PGPUB	000000544544.07
-	3	((414/\$ or 901/\$).CCLS.) and (((tooth or teeth) near3 ratio)	USPAT;	2003/05/15 14:27
	420	with pulley)	US-PGPUB	2003/05/15 14:32
_	439	((414/\$ or 901/\$).CCLS.) and (ratio with (pulley or arm))	USPAT; US-PGPUB	2003/03/15 14.32
	73	(((414/\$ or 901/\$).CCLS.) and (ratio with (pulley or arm))) and	USPAT:	2003/05/15 14:28
-	13	(((414/5 of 901/5).CCLS.) and (1atio with (pulley of arm))) and ("2:1" or "1:2")	US-PGPUB	2003/03/13 14.20
	2144	(414/\$ or 901/\$).CCLS.) and (angle with rotation)	USPAT:	2003/05/15 14:33
-	2144	((414) \$01901).COES.) and (angle with rotation)	US-PGPUB	2000/00/10 14:00
_	214	((414/\$ or 901/\$).CCLS.) and (angle with rotation) and (arm	USPAT:	2003/10/24 02:21
_	217	with orientation)	US-PGPUB	2000/10/24 02.21
_	19	((414/\$ or 901/\$).CCLS.) and (angle with rotation) and	USPAT:	2003/05/15 16:21
	"	(constant adj orientation)	US-PGPUB	2000/00/10 10:21
_	3	(("6471504") or ("6105454") or ("5860331")).PN.	USPAT;	2003/10/24 02:05
	ĺ	(0	US-PGPUB	
-	29	(414/\$.ccls, or 901/\$.ccls, or 425/\$.ccls.) and (injection with	USPAT:	2003/10/24 02:23
		machine) and ((robot or robotic) with arm) and (arm with	US-PGPUB	
		rotation)		
_	18	brett.inv. and (robotic with arm)	USPAT;	2003/10/24 02:21
		,	US-PGPUB	
_	31	matsui.inv. and robot	USPAT;	2003/10/24 02:25
			US-PGPUB	
-	345	(robot with arm) and (arm with rotation with base)	USPAT;	2003/10/24 02:25
			US-PGPUB	
-	110	((robot with arm) and (arm with rotation with base)) and pulleys	USPAT;	2003/10/24 02:25
			US-PGPUB	